



EU-Project

FERRYBOX

**From On-line Oceanographic Observations
to Environmental Information**

2003 - 2005



**Summary
and
Selected Results**

**Contract number: EVK2-2002-00144
Coordination: GKSS Research Centre**



EU-Project „FerryBox“

Objectives and Conclusions

Objectives of the Project

The overall objective of FerryBox has been to show that ship born instrumentation can cost effectively deliver information of immediate scientific value and help to solve environmental problems, and that FerryBox systems provide a reliable instrument for efficient monitoring and management in European waters. The FerryBox systems consist of a fully automated flow-through system with sensors and automatic analysers for the measurement of physical, biological and chemical parameters, which uses ferryboats and other ships of opportunity as the carrier system. The data can be assimilated into prognostic numerical models to improve their accuracy. Finally, it can be concluded that such FerryBox systems offer potentials for a wider European contribution to GOOS, with incorporation of European sensor and information technology.

Benefits of the Project

The benefits of the project are:

- Understanding the seasonal changes in the most important water quality parameters
- Improving our knowledge on the natural ranges in parameters and in ranges impacted by human activities
- Providing baseline data for the assessment of long-term trends in coastal and marine waters
- Providing data sources for operational & ecological models on water transport & environmental parameters
- Delivering a large set of calibrated and quality assured ground truth data for remote sensing applications (e.g. for the ENVISAT).

Conclusions

The project has proven and demonstrated that:

- Ferrybox systems provide a reliable network for efficient monitoring and management
- Ferrybox data are useful and beneficial for a variety of marine research and operational oceanography objectives and can contribute to improve (operational) numerical model and forecasting applications including their accuracy and prediction quality by assimilating field data with higher spatial and temporal observation density.
- Ferrybox systems offer large potentials for a wider European contribution to the GOOS
- European Ferrybox technologies and sensors as well as related scientific, operational, observational and operational methodologies are at the leading edge in this area.

New Developments

During the last GOOS Steering Committee (GSSC) meeting in Paris (6-8. March 2006) the FerryBox concept has been adopted as a Pilot project for the Coastal Implementation of GOOS (Global Ocean Observation System). This will give additional recognition of the FerryBox concept on a global scale.

The Ferry Routes within the Project

Baltic Sea:	Helsinki (FI) – Travemünde (D) and Helsinki (FI) – Tallinn (EE)
Skagerrak:	Oslo (NO) – Hirtshals (DK)
North Sea:	Cuxhaven (DE) – Harwich (UK)
Wadden Sea:	Den Helder – Texel Island (NL)
Irish Sea:	Liverpool (UK) – Belfast (Ireland)
English Channel	Southampton – Isle of Wight (UK)
Bay of Biscay :	Portsmouth (UK) – Bilbao (ES)
Aegean Sea:	Athens – Heraklion (GR)



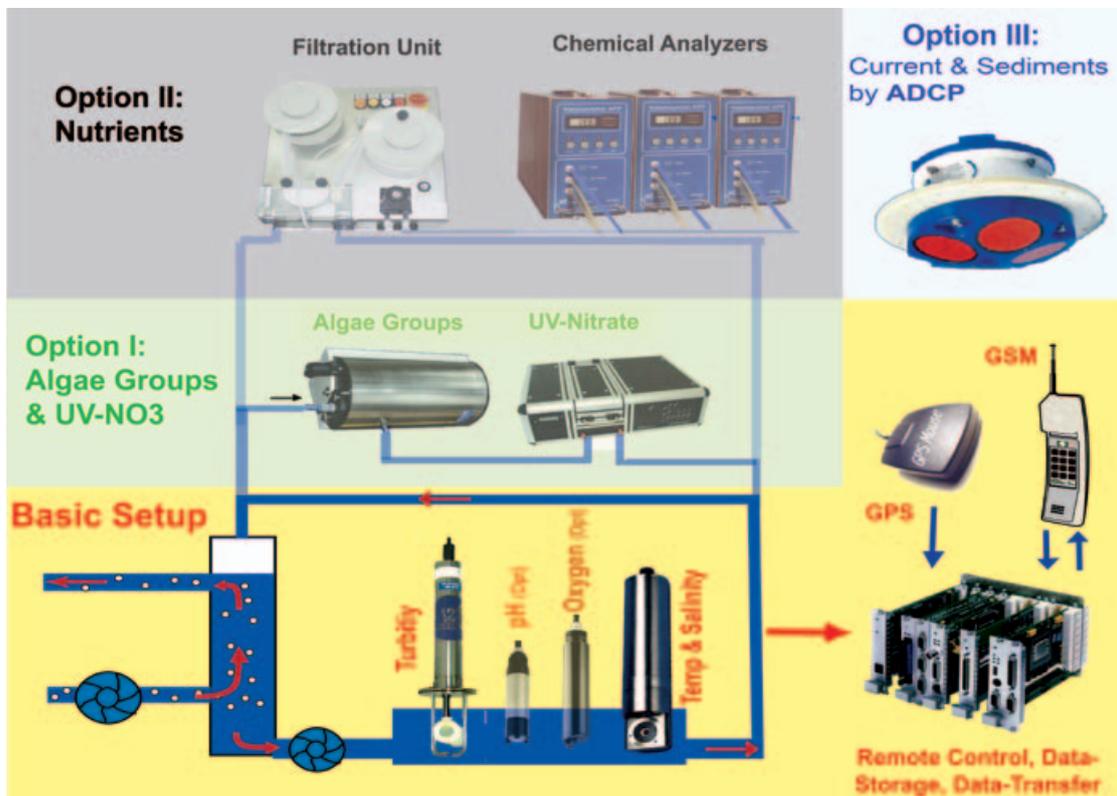


The FerryBox

Ferries used in the Project



The Principle



The principle of a FerryBox consists of a flow-through system with different sensors for oceanographic, chemical and biological parameters. It is fully automated and some systems provide automated cleaning and antifouling procedures. The data are stored on the ferry and may be transferred to shore by mobile phone or satellite telemetry.



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Achievements and Recommendations

Project Achievements

The project successfully operated a standard set of sensors (temperature, salinity, turbidity, chlorophyll-fluorescence) on 9 different routes in the Baltic Sea, the North Sea, the Channel, the Irish Sea, the Bay of Biscay and the Aegean Sea (Mediterranean). The majority of the systems were highly reliable with over 90 % of all possible data being recorded and meeting quality control criteria

The following scientific achievements were reached:

- Impact of frontal systems on the biological activity
- Change of the physiological state of phytoplankton prior, during and after a bloom
- Magnitude and variations in sediment transport in a tidal inlet
- Assessment of inter- and intra-annual variability in concentrations of nutrients and plankton species
- Comparisons of the FerryBox data to satellite based data sets
- Assimilation of FerryBox data into numerical models.

The strategy developed using FerryBoxes successfully demonstrated that a cost effective monitoring system is available for operational services and that an effective linkage with data buoy observations and remote sensing methods with FerryBox systems exists.

The acceptance of the system is well documented before the finalization of the project through installation of further systems on board of other Ferries and vessels of operational services in Norway and the Netherlands.

Recommendations

Authorities, agencies or scientific institutions that consider a potential future implementation of a ferry system in their research/monitoring should consider the following recommendations:

1. In the planning phase a careful assessment should be carried out to judge if the ferry/ship route meets the objectives of the monitoring or research tasks. For example: Will surface measurements from a ship yield enough information to reach the objective or has a combination with buoys to be considered?
2. In order to choose the appropriate FerryBox system for the planned task, helpful hints can be obtained from the Final Report of the project (www.ferrybox.org).
3. The type of instrumentation, i.e., sensors or analysers, their applicability and their limitations for the intended task and the meaningfulness of the scientific results obtained with these instruments should be assessed in advance. More details can be found in the deliverables of the Final Report.
4. The effort/expenditure of the maintenance that depends on the number and type of measured parameters should be carefully observed. More details can be found in deliverable D-6-2 “Cost-Benefit Estimation Report”.
5. Even when a FerryBox system is highly automated, the potential user should keep in mind that regular (1-2 days) data checks and regular maintenance/calibrations (weekly to bimonthly, depending on instrumentation and required accuracy) are needed.



Costs and Benefits

Technical and Operational Benefits

- Compared to offshore deployed devices the operation costs of Ferrybox systems are drastically lower as maintenance works can be conducted in one of the ports the vessel is calling routinely which, however, should be located preferably nearby to the operating institution.
- Ferrybox systems and their sensors and components are much easier and simpler to design, construct and operate than stand-alone marine in-situ devices.
- Ferrybox systems do not need a specially designed platform and can be installed on almost all seagoing vessels providing their owners and operators allow it. Installation costs and efforts are relatively low as available infrastructure on the ship like space, water supplies, cable booms, and communication devices can be used supportively.
- Many technical problems typical for stand-alone marine measuring systems can be entirely omitted. This includes especially constraints in availability of electric energy, installation and consumable storage space as well as protection of several components against harsh marine environments and prevention measures of longer-term fouling with associated maintenance efforts.

Estimated Costs

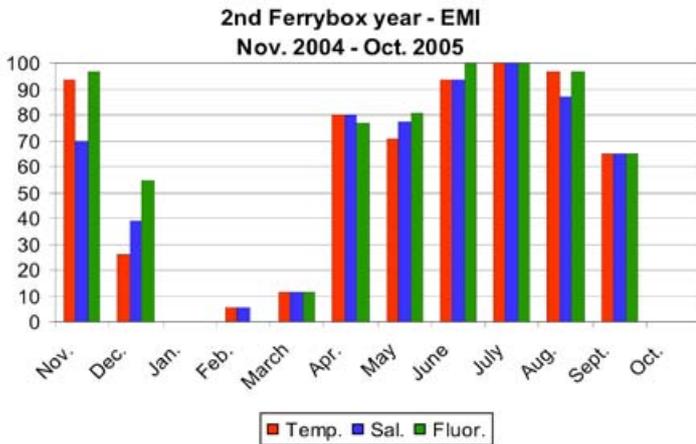
FerryBox Basic System (EUR)			
Standard FerryBox	CTG	4H Jena	Includes remote control and data storage computer, GPS system, basic sensor set (temperature, salinity, turbidity, chlorophyll-a fluorescence), Software
	67,000	37,000-43,000	
Shore-based station	n.a.	6,500	Database and presentation system on PC
Installation onboard (pumps, tubes, plumbing etc.)	4,000 – 12,000		depending on ship and configuration of the FB (standard or enhanced)
For the 4H Jena system an automatic antifouling unit is included			
Additional Sensors/Analysers (appr. EUR)			
Oxygen-Optode & pH	4,000		
UV- nitrate Detector	15,000		UV detection (only for nitrate)
Filtration unit	1,500		For wet chemical analysis of nutrients
Nutrients (single channel)	22,000		Wet chemical analysers
Nutrients (double channel)	25,000		
Algal groups	19,000		Excitation at different wavelengths to discriminate between different algal groups (pigments)
ADCP	36,000		
pCO ₂ Measuring System	60,000 – 70,000		
Operation Cost (EUR per year)			
Consumables and spare parts	3,000 – 12,000		
Communication fees	600 – 2,400		Depending on data volume
Reference analysis (water samples)	500 – 4,000		Laboratory analysis of salinity, chlorophyll and nutrients
Maintenance of sensors (CTD, fluorescence)	1,000 – 2,000		Yearly check and recalibration by the manufacturer
Operation Cost (person months per year)			
Operation, maintenance and supervision (basic system)	3 - 6		Standard system
Additional sensors (e.g. nutrients)	3 - 10		Depending on system complexity
Data dissemination including Internet services	1 - 6		Depending on the complexity of internet services



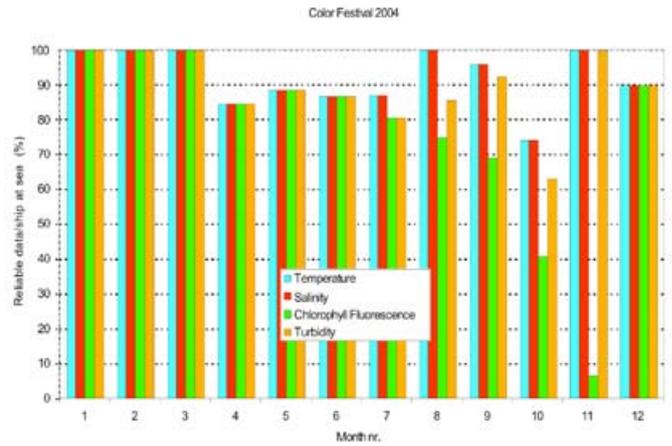
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Reliability

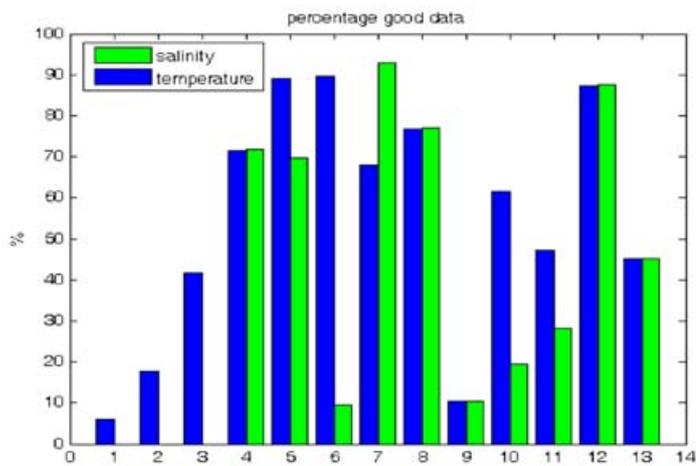
Data Availability for Temperature/Salinity for November 2004 to October 2005



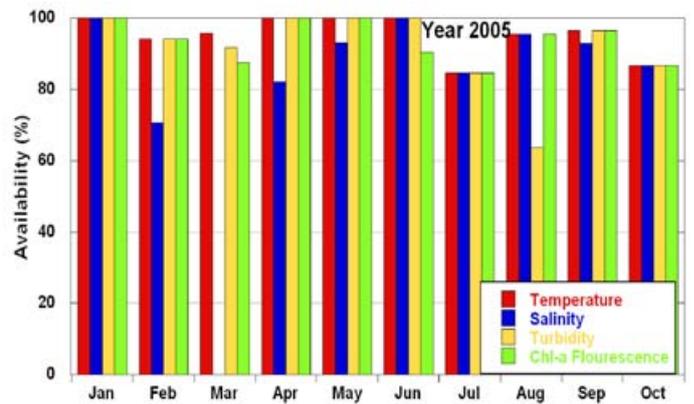
Data Availability on the Route Tallin-Helsinki (EMI&FIMR)



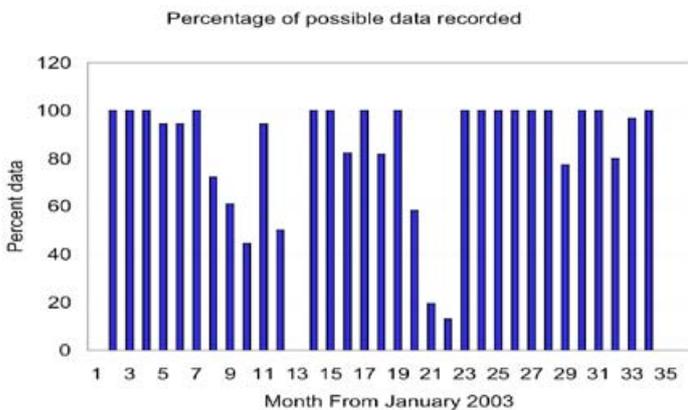
Data Availability on the Route Hirthhals-Oslo (NIVA)



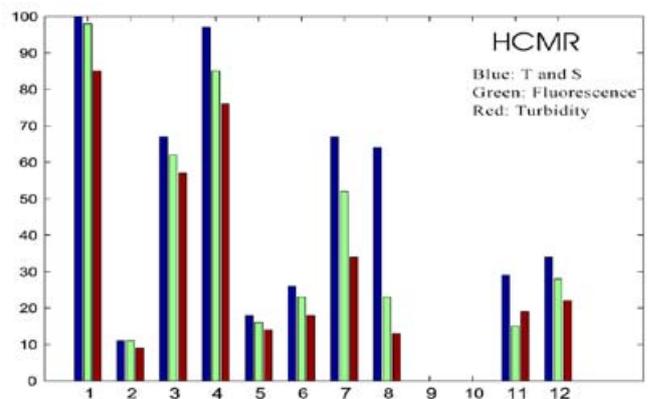
Data Availability on the Route Den Helder- Texel (NIOZ)



Data Availability on the Route Cuxhaven-Harwich (GKSS)



Data Availability on the Route Southampton-Bilbao (NOC)



Data Availability on the Route Athens-Heraklion (HCMR)

Conclusion: The experiences of the consortium after two years of operating the different FerryBoxes show that after solving some start-up problems most of the FerryBox systems were running very well producing high rate of reliable data. The availability of reliable data related on the number of cruises was between 50 and 100%. The data availability depends on the type of sensor or analyser. For example, nutrient analysers are more complex and prone to failure than more simple sensors as temperature, salinity and chlorophyll. Automated cleaning procedures enhance the data availability.

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Technical Details of the Different FerryBox systems

Route no.:	R-1-A	Operator:	FIMR
Description		Remarks	
Route:	Hel싱k (Finland) – Travemünde (Germany)		
Ship:	MS Finnpartner		
Ferry company:	Finnlines, Finland		
System type:	Flow through system		
Frequency:	Flow through data three times per week. Automated sampling for phytoplankton, chlorophyll-a and nutrients once per week from April to September.		
Travel time:	36 hours		
Control:	Once per week		
Features:	Brackish water salinity about 5 – 7 psu		
Measured parameters:	Conductivity, water temperature, fluorescence; automated samples for nutrients, chlorophyll-a, phytoplankton		
Spatial resolution:	Flow through system: salinity, temperature and fluorescence every 200 m Water sampling for laboratory analysis at fixed latitudes		
Remote control:	No		
Data transfer:	Diskette		
Data storage:	Every 20 s outside harbour area		
Depth of water intake:	5 m		
Web site:	http://www2.fimr.fi/en/fimerikaanta.html		

Route no.:	R-1-B	Operators:	FIMR and EMI
Description		Remarks	
Route:	Hel싱k (Finland) – Tallinn (Estonia)		
Ship:	M/S Romantika		
Ferry company:	Tallinn, Estonia		
System type:	Flow through system		
Frequency:	Flow through data twice per day. Automated sampling for phytoplankton, chlorophyll-a and nutrients once per week.		
Travel time:	3.5 hours		
Control:	Once per week		
Features:	Brackish water salinity about 5 psu		
Measured parameters:	Conductivity, water temperature, fluorescence; automated samples for nutrients, chlorophyll-a and phytoplankton		
Spatial resolution:	Flow through system: salinity, temperature and fluorescence approximately every 200 metres Water sampling for subsequent laboratory analysis at fixed latitudes		
Remote control:	No		
Data transfer:	Diskette		
Data storage:	Every 20 s outside harbour area		
Depth of water intake:	4 m		
Web site:	http://www.fimr.fi/en/fimerikaanta.html		

Route no.:	R-2	Operators:	NIVA
Description		Remarks	
Route:	Oslo (Norway) – Hirtshals (Denmark)		Operation from August 2001. New harbour in Denmark in April 2006.
Ship:	Color Festival		
Ferry company:	Color Line		
System type:	Flow through system. Design of NIVA.		
Frequency:	1 round trip per day		
Travel time:	Night time 12 hours, day time 6 hours		
Control:	The system is controlled with a LabView software.		
Features:	Automatic or remotely controlled water sampling and above water radiance measurements for satellite validation.		Water samples triggered during satellite overpass.
Measured parameters:	Conductivity, water temperature, turbidity, Chl-a fluorescence, light sensors. Samples collected for Chl-a with HPLC and TSM measurements		
Spatial resolution:	Every 400 to 800 m depending on night or day measurements 1 observation per minute.		
Remote control:	Via satellite link		
Data transfer:	Continuous over satellite link to NIVA database		
Data storage:	Onboard and database at NIVA		
Depth of water intake:	3-4 meters		
Web site:	http://www.ferrybox.no		Public presentation of the data

Route no.:	R-3	Operator:	GKSS
Description		Remarks	
Route:	Cuxhaven (Germany) – Harwich (United Kingdom)		Reconstructed system in operation on new ferry boat since September 2003.
Ship:	Duchess of Scandinavia		
Ferry company:	DFDS Seaways		
System type:	Flow through system		
Frequency:	1 round trip every 2 days		
Travel time:			
Control:	Supervised by an industrial programmable logic control		
Features:	Automatic cleaning procedure by acidified tap water after each trip in the harbour		
Measured parameters:	Conductivity, water temperature, turbidity, dissolved oxygen, fluorescence, ammonium, nitrate/nitrite, phosphate, silicate, different algae groups		
Resolution:	Approximately 100 m – every 10 s; nutrients approximately 6 km – every 10 minutes		
Remote control:	System can be remotely controlled by GSM		
Data transfer:	Controlled by an industrial standard PC		
Data storage:	Controlled by an industrial standard PC		
Depth of water intake:	5 m		
Web site:	http://coast.gkss.de/projects/ferrybox		

Route no.:	R-4	Operator:	NIOZ
Description		Remarks	
Route:	Den Helder – Texel (the Netherlands)		Upgraded system in operation since 2003.
Ship:	Schulpengat		Display in passenger lounge.
Ferry company:	TESO (Texels Eigen Stoomboot Onderneming)		
System type:	Flow through system and hull mounted acoustic current profiling system (ADCP)		
Frequency:	Every 30 minutes, daily between 06.00 and 22.00 local time		
Travel time:			
Control:	External logging and display on ferry		
Features:			
Measured parameters:	Salinity, water temperature, fluorescence, turbidity, horizontal current speed and direction		Optical measurements (fluorescence, turbidity) are suspect due to air bubbles in the system
Resolution:	5 – 10 m		
Remote control:	By telemetry		
Data transfer:	Transferred to the nearby research centre by telemetry		
Data storage:	At the nearby research centre		
Depth of water intake:	0.50 m		
Web site:	http://www.nioz.nl/en/deps/fys/nioztoos/orhtml		

Route no.:	R-5	Operator:	NERC.POL
Description		Remarks	
Route:	Liverpool (UK) – Belfast (Northern Ireland)		
Ship:	Liverpool Viking		
Ferry company:	Norse Merchant		
System type:	Flow through system		
Frequency:			
Travel time:			
Control:	External logging		
Features:			
Measured parameters:	Conductivity, water temperature, turbidity, fluorescence		
Resolution:	Approximately 300 m (sampling frequency 30 s)		
Remote control:	None		
Data transfer:	External logging, plus data telemetry of spot values via OrbComm satellite every 15 minutes - started 18 October 2004.		
Data storage:	Files, final data banked at BODC		
Depth of water intake:	3.5 m		
Web site:	http://coastbbs.pol.ac.uk		

Route no.:	R-7	Operator:	NERC.NOC and IEO
Description		Remarks	
Route:	Portsmouth (UK) – Bilbao (Spain)		FerryBox system fully operational since April 2002.
Ship:	Pride of Bilbao		New logger fitted October 2004. System expanded in 2005
Ferry company:	P & O Ferries Ltd.		
System type:	Flow through system in parallel to ship's refrigerator cooling water. Continuous flow with manual shut off.		
Frequency:	In 2002-2004: 1 round trip per week – February to mid March, 2 round trips per week – mid March to early January In 2005 shuttle service from late January to new year 2006		
Travel time:	About 33 hours per crossing, 72 hours per round trip		
Control:	Data management: PC with UNIX from 2004 DOS		
Features:	Modular system, extendable for other chemical sensors/analysers; anti-fouling prevention by weekly manual inspection and cleaning.		
Measured parameters:	Conductivity, water temperature, turbidity, fluorescence. From 2005 oxygen, pCO2		
Resolution:	At full speed (20 knots) data rate is 1 Hz giving a spatial resolution of approximately 10 metres. Data are mapped with 5 minute (time) resolution.		Comparison with ISAR hull temperature suggest mixing in the sea chest smooths data.
Remote control:			
Data transfer:	OrbComm satellite link and e-mail. At 5 minute interval data sample sent to web page. Weekly manual collection of 1 Hz data		Public access to un-calibrated 5 minute averages via web page.
Data storage:	Combined file of all data channels including GPS collected in engine room and backed up to the ISAR system computer on bridge SQL data base at NERC BODC for web access. 1 Hz data stored at NOC. 5 minute averaged data sent to BODC as individual parameter files		
Depth of water intake:	5 m		
Web site:	http://www.noc.soton.ac.uk/ops/ferrybox_index.php		

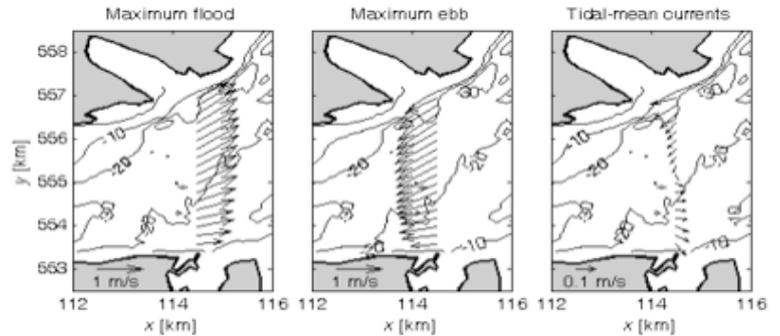
Route no.:	R-8	Operator:	HCMR (formerly NCMR)
Description		Remarks	
Route:	Athens – Heraklion (Greece)		FerryBox system operational with data gaps during November 2003 to October 2004
Ship:	KRITI II		
Ferry company:	Anek Lines		FerryBox system not in operation after October 2004 because 1) of technical problems and 2) the ship was moved to another route in the Ionian Sea. Operation is expected to recommence in early 2005 independently of ferry route and after repair/improvement by the manufacturer.
System type:	Flow through system		
Frequency:	1 trip every night in alternating directions		
Travel time:	9 hours		
Control:	Supervised by an industrial programmable logic control		
Features:	Automatic cleaning procedure (by acidified water) in the harbour after each trip.		
Measured parameters:	Conductivity, water temperature, turbidity, fluorescence		
Resolution:	Raw measurements every 1 s - approx. every 10 m; stored averages every 60 sec - approx. every 600 m		
Remote control:	Limited remote access on the various settings via GSM when sailing in GSM covered areas.		
Data transfer:	Cell phone data telemetry via industrial standard PC		
Data storage:	On board and on the land station controlled by industrial standard PC		
Depth of water intake:	Approximately 5 m		
Web site:	http://www.poseidon.ncmr.gr/ferrybox		



Example I: Water and Sediment Transport in the Mars Diep (NIOZ)

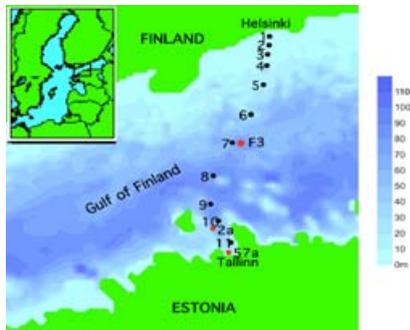


Ferry Route Texel to Den Helder

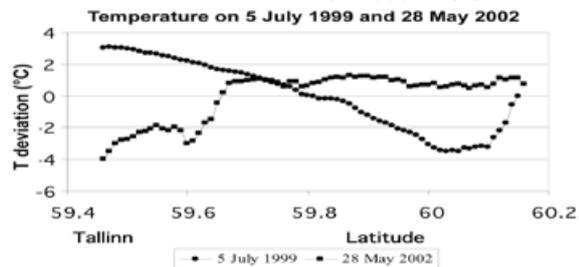


Selected Scientific Results

Example II: Upwelling in the Gulf of Finland (EMI)



The ferry route



Temperature deviations along the ferry line Tallinn-Helsinki showing upwelling events near the southern (28 May 2002) and northern (5 July 1999) coasts of the Gulf of Finland developing after 5 days of easterly or westerly winds, respectively.

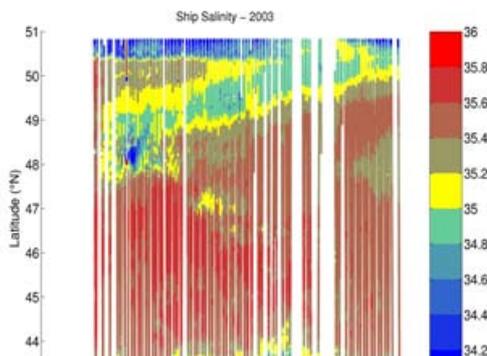
In the Gulf of Finland the seasonal thermocline is usually situated at the depth of 10-20 m. The phosphocline is located in the upper part of the thermocline and the nitracline is about 5 m deeper (Laanemets et al., 2004). Thus, the upwelling events and wind induced mixing favour enrichment of the near-surface layer mainly with phosphate. Cold upwelled water appears very close to the shoreline near the southern (Estonian) coast where the slope is steeper while it stays offshore from the Finnish coast.

Since nutrient concentrations are not measured in a routine basis on the ferry route the nutrient input into the near-surface layer caused by the upwelling events could be estimated on the basis of unattended temperature measurements. One can make a rough assumption that the phosphate input from below the thermocline is proportional to the temperature difference between upwelled water and the surrounding water. An upwelling index is introduced and calculated as a mean temperature deviation in a 20-km wide coastal zone from the cross-gulf average temperature for every day. Operational estimates of intensities of pre-bloom upwelling events are used to forecast the late summer cyanobacterial blooms in the Gulf of Finland (Laanemets et al., 2006). Analysis of Ferrybox data from 1997-2004 revealed a good correlation between the seasonally integrated intensities of upwelling events (from 1 May until 30 June) and the integrated cyanobacterial bloom biomasses (Lips, 2005).

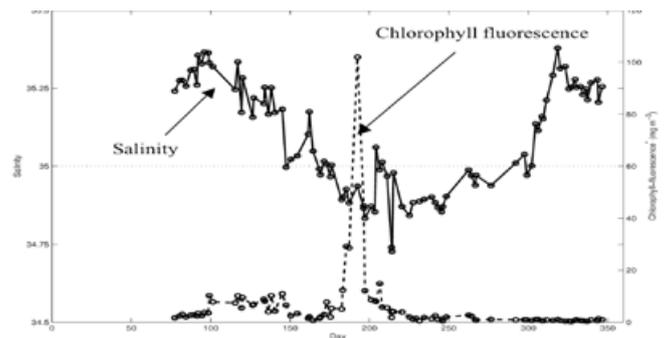
Example III: The origin of Low salinity intrusions in the western English Channel and its Consequences for a Plankton Bloom(NOC)



The ferry route



Sea surface salinity between Portsmouth and Bilbao in 2003 showing low salinity waters entering the western English Channel (~48°N)



Timeseries data of chlorophyll-fluorescence and salinity showing the coincidence in the timing of the bloom in *Karenia mikimotoi* and the arrival of low salinity water in the western English Channel (49.1°N, 4.1°W)

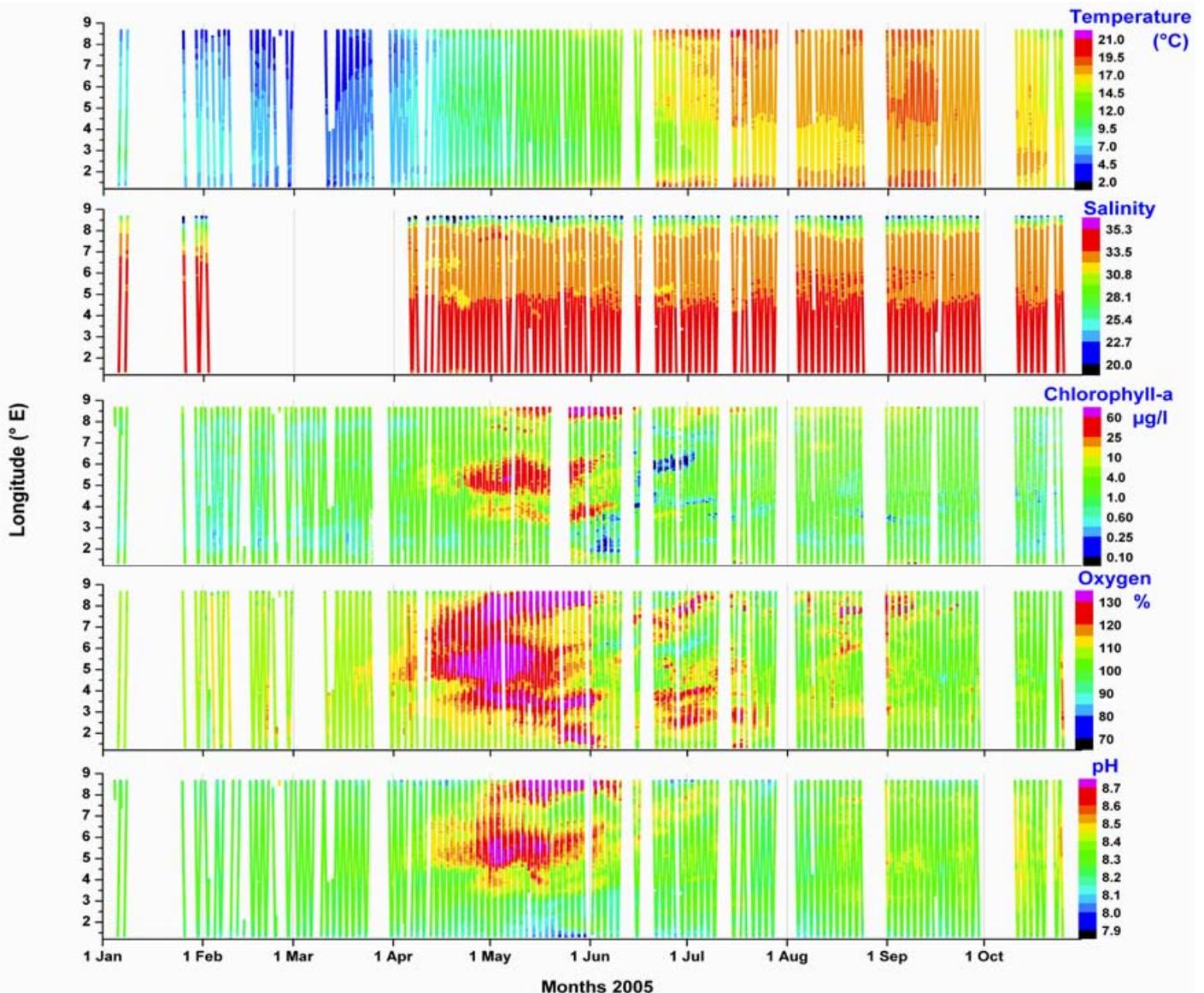
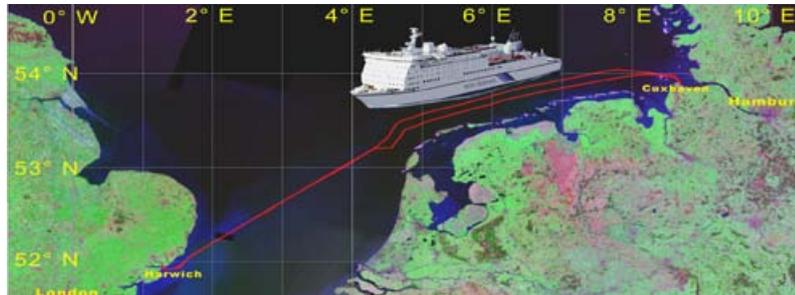
During FerryBox measurements low salinity (<35) surface waters (LSSW) at the southern entrance to the western English Channel (48.5°N, 5.1°W, near Ushant) were observed in late winter (March-April) in three successive years (2002 - 2004). The LSSW intruded into the western English Channel in each year, suggesting a common phenomenon. The source of the LSSW is the northward spreading plumes from the Loire and Gironde along the French Atlantic coast (Kelly-Gerreyn et al. 2006).

Within 2 days of the arrival of the LSSW an intense monospecific bloom (~100 mg Chl a m⁻³) of the dinoflagellate *Karenia mikimotoi* was observed. It is proposed that changes in surface density due to these low salinity intrusions influences the summer bloom intensity of *K. mikimotoi*. The hypothesis is that the low salinity intrusions enhance blooms of *K. mikimotoi* through increased buoyancy of the upper water column and thereby influence the observed interannual variability in the abundance of this phytoplankter in the western English Channel.



Selected Scientific Results

Example IV: Algae Bloom in the Southern North Sea (GKSS)



Temporal development of temperature, salinity, chlorophyll, oxygen and pH along the ferry transect in 2005 (GKSS)

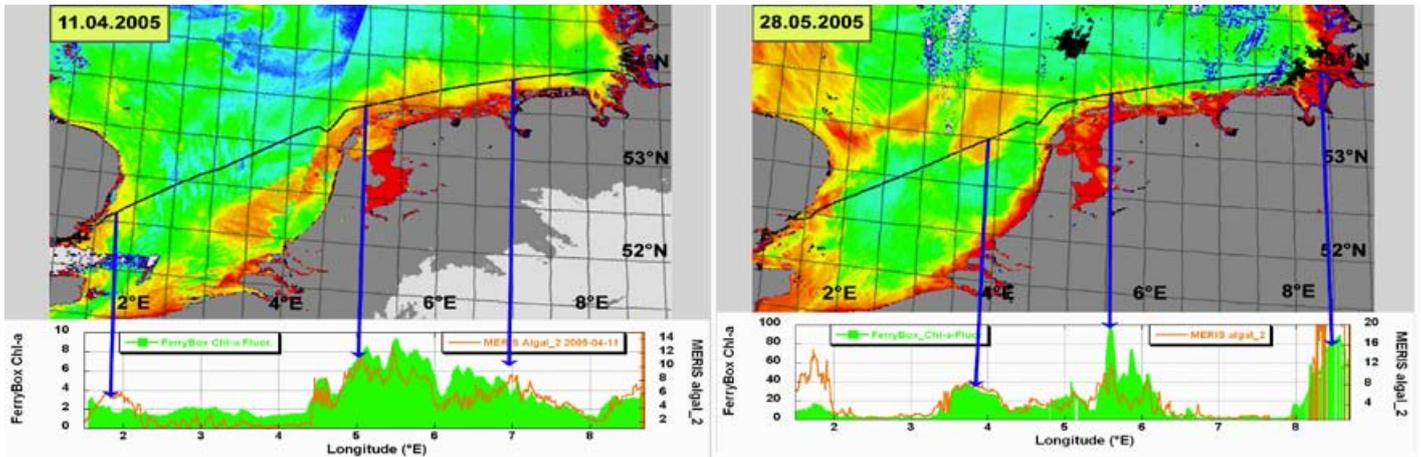
The plankton blooms in the Southern North Sea always start in spring near the Belgium coast. With regular FerryBox measurements this phenomena can be more closely resolved in time and space and the extent of the primary production can be estimated. From the diagrams above the typical spring bloom in April-May can be seen not only from the chlorophyll but as well from oxygen and pH. The high productivity is evident from oxygen oversaturation of more than 130% and high pH values of >8.6. Only with such (temporal) high resolution measurements by means of a FerryBox this information about algal processes can be obtained.



Selected Scientific Results

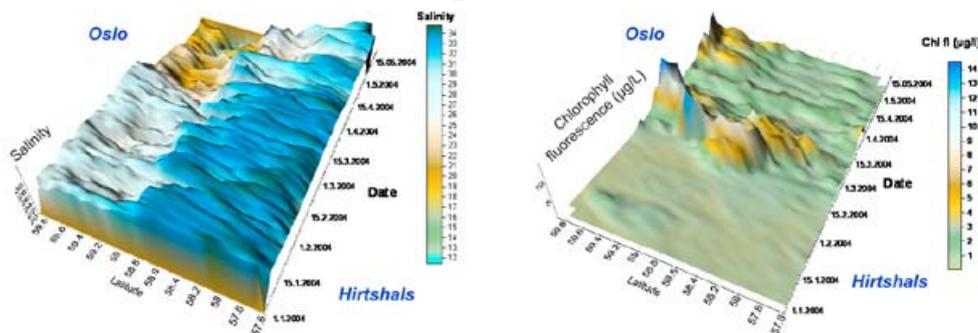
Example V: Comparison of FerryBox data with data from remote sensing (GKSS)

Another application of a FerryBox is the comparison with satellite data: 1) FerryBox measurements can be used for validation/calibration of satellite data for suspended matter and chlorophyll. 2) Satellite data expand the view of the FerryBox (which is limited to the transect) to the area. Whereas the algorithms for class-1 water (open ocean with only little turbidity and yellow substance) are well accepted, improvements are needed for turbid class-2 waters near the coast. For this FerryBox measurements are an excellent tool.



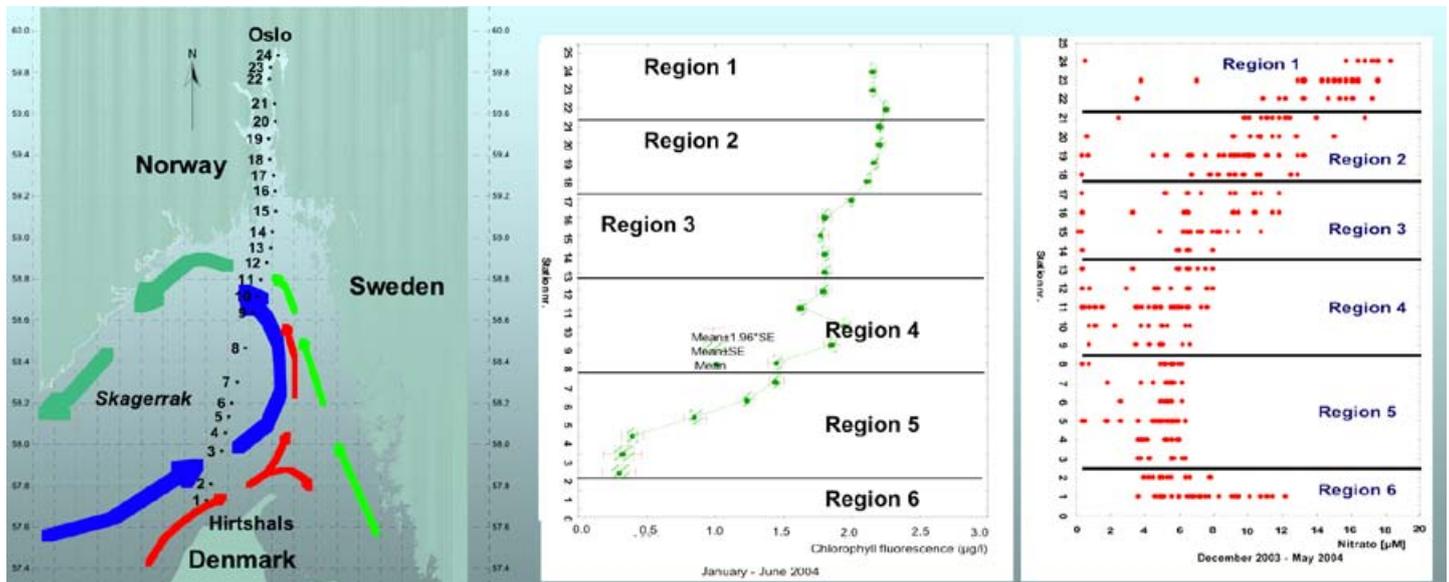
Chlorophyll concentration map of May 11th and June 28th from ENVISAT/MERIS (top). The diagrams below show a comparison of pixels extracted along the FerryBox transect and data measured by the FerryBox. Due to the time shift between the ferry cruise and the satellite pass a correction of the water movement by a numerical model has been applied (model calculation by the BSH).

Example VI: Classification of Water Masses (NIVA)



Development of salinity and Chlorophyll between Oslo and Hirtshals in spring 2004 (left). The development of the spring bloom in the Oslo Fjord can clearly be seen.

Classification of water bodies into 6 regions according to the chlorophyll- and nitrate concentrations (below). For a more detailed classification other winter nutrients are included in the classification scheme.



FerryBox measurements are a useful tool for routine water quality monitoring. The frequent data can be utilised to define regions which meet specific water quality criteria.



Conclusions

The project achieved its objectives very effectively with operating and comparing different European FerryBox systems. The generated data are available from the website and from the British Oceanographic Data Centre (BODC). The series of scientific studies, numerical model experiments, data assimilation and validation exercises of satellite-borne remote sensing data have all achieved results which have or are being written up in peer reviewed scientific papers. Its success is shown in the large number of follow-on and associated activities that are happening or planned, as well as by increasing utilisation of FerryBox systems by other groups. Overall the project has demonstrated that the FerryBox concept is one which both provides data of scientific value and that can be expected to make a cost effective contribution to future European (and global) operational marine monitoring and management systems.

Project Participants

Organisation		Website	Contact
	GKSS (Coordinator)	GKSS Research Centre Institute for Coastal Research	www.gkss.de Franciscus Colijn colijn@gkss.de
	NERC.NOC	National Oceanography Centre-NERC.NOC Southampton University - Natural Environment Research Council	www.soc.soton.ac.uk David Hydes djh@noc.soton.ac.uk
	NIOZ	Royal Netherlands Institute for Sea Research Department of Physical Oceanography	www.nioz.nl Herman Ridderinkhof rid@nioz.nl
	FIMR	Finnish Institute of Marine Research	www.fimr.fi Seppo Kaitala seppo.kaitala@fimr.fi
	HCMR	Hellenic Centre for Marine Research	www.hcmr.gr Harilaos Kontoyiannis hk@ath.hcmr.gr
	NERC.POL	Proudman Oceanographic Laboratory	www.pol.ac.uk Roger Proctor rp@pol.ac.uk
	NIVA	Norwegian Institute for Water Research	www.niva.no Kai Sørensen kai.soerensen@niva.no
	HYDROMOD	HYDROMOD Scientific Consulting	www.hydromod.de Klaus Pfeiffer pfeiffer@hydromod.de
	CTG	Chelsea Technology Group	www.chelsea.co.uk G. W. Neal bneal@chelsea.co.uk
	IEO	Spanish Institute of Oceanography Centro Oceanográfico de Santander	www.ieo.es Alicia Lavin alicia.lavin@ieo.es
	EMI	Estonian Marine Institute Marine Systems Institute (in cooperation with the Estonian Maritime Academy)	www.sea.ee Inga Lips inga@sea.ee

Further Information

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