

Understanding sea surface
temperature measurements made
by 4 different instrumental methods
on a Ship of Opportunity.

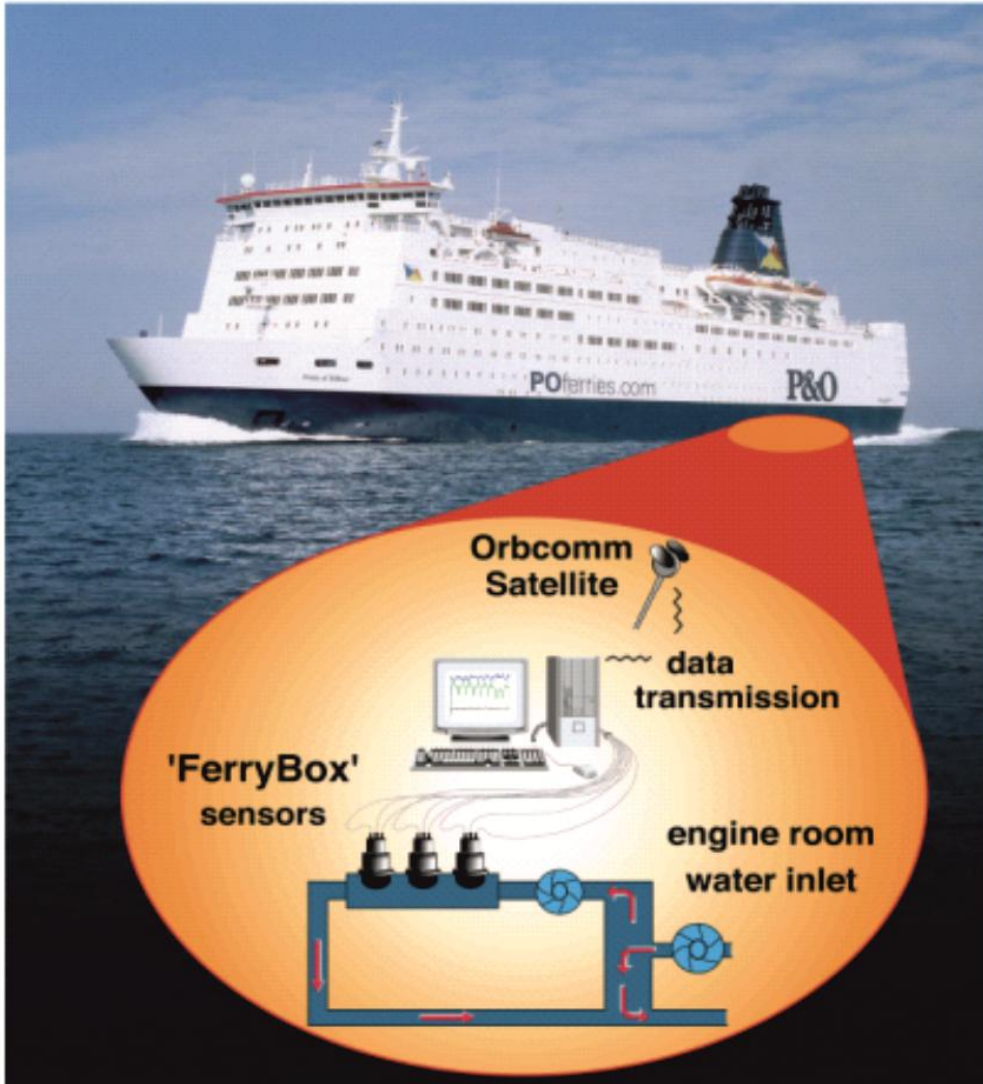
Mark Hartman

NOC

- The ship and the route
- Sensor descriptions
- Software Filter development
- Results
- Conclusions

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The ship

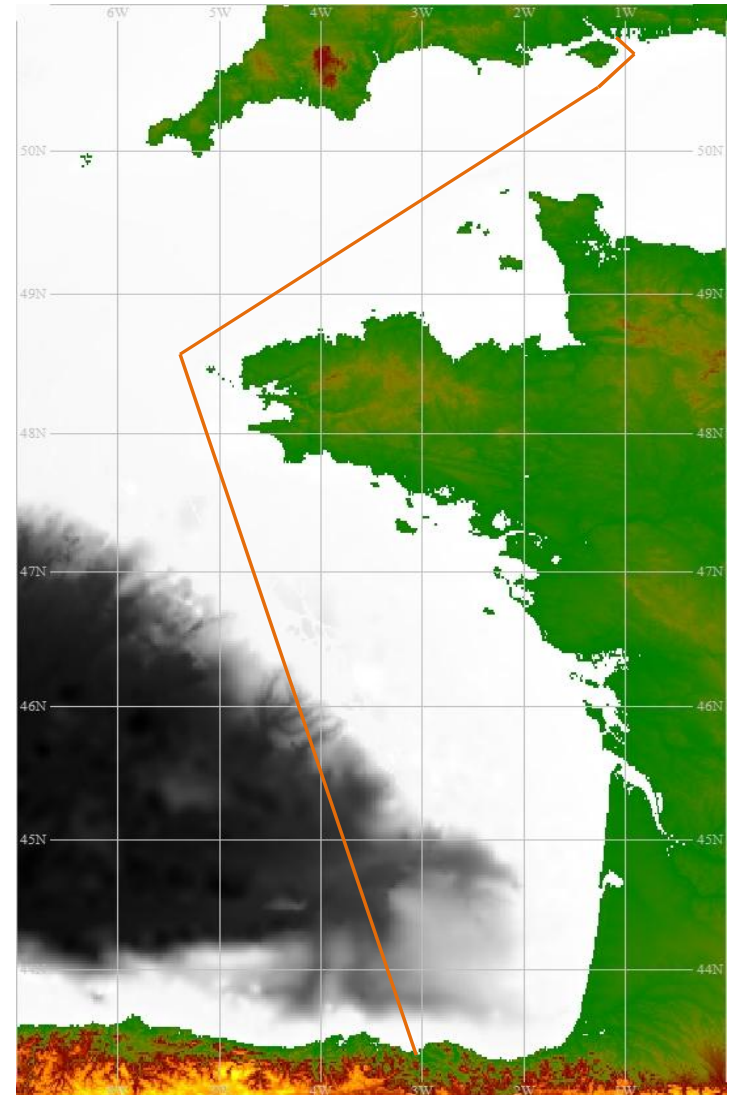


- P&O MV Pride of Bilbao
- Ferrybox 2002 - 2010
- Speed 20 knots

The route

- Portsmouth, UK to Bilbao, Spain
- 1000 km each way
- There and back takes 3 days
- 3 hour turnaround in port

Portsmouth, UK



Bilbao, ES

- The ship and the route
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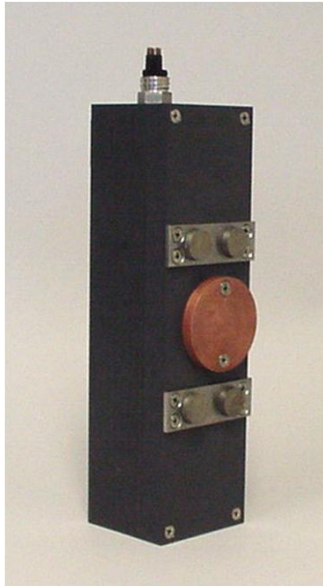
- Sensors
 - Hull
 - ISAR
 - CPR
 - Ferrybox

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SBE 48 Hull sensor

- 5 metres deep
- Hull temperature
- Stable thermistor
- Every 30 seconds

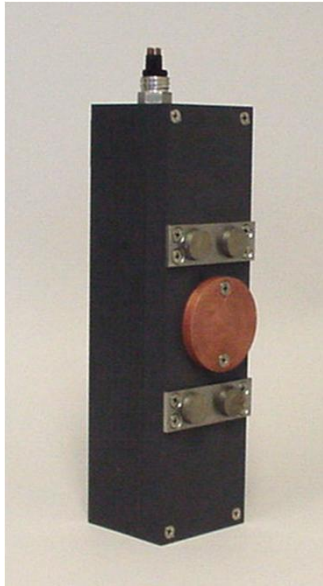
Hull
Sensor
location



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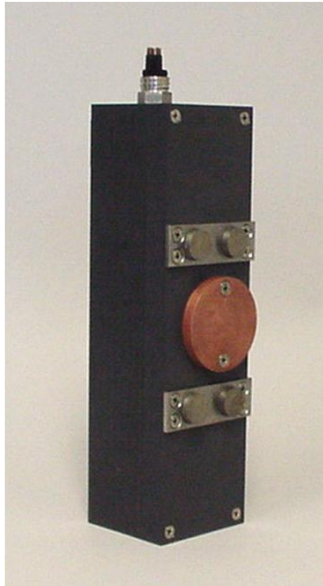
Sensor location



SBE 48 Hull sensor

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Sensor
location



- Sensors
 - Hull
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 - Ferrybox

ISAR - Infrared Sea surface temperature Autonomous Radiometer



- Bridge Top (35 metres)
- Skin temperature
- 1 minute average
- Every 3 minutes

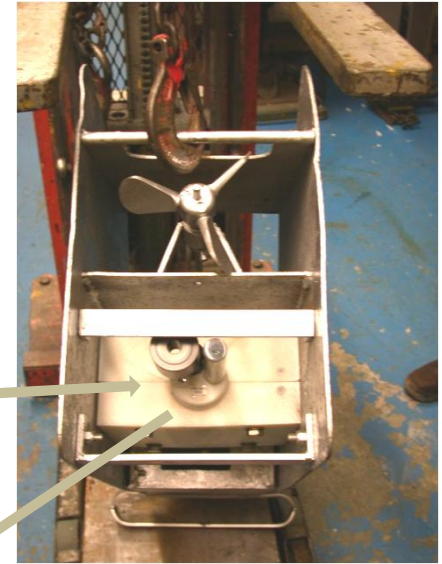


- Sensors
 - Hull
 - ISAR
 - CPR
 - Ferrybox

RBR thermistor

- Thermistor on a towed body
- 2 minute sample
- 5 metres depth

RBR thermistor



CPR - Continuous Plankton Recorder



View of the ship's wake



- Sensors
 - Hull
 - ISAR
 - CPR
 - Ferrybox

Ferrybox flow through housing

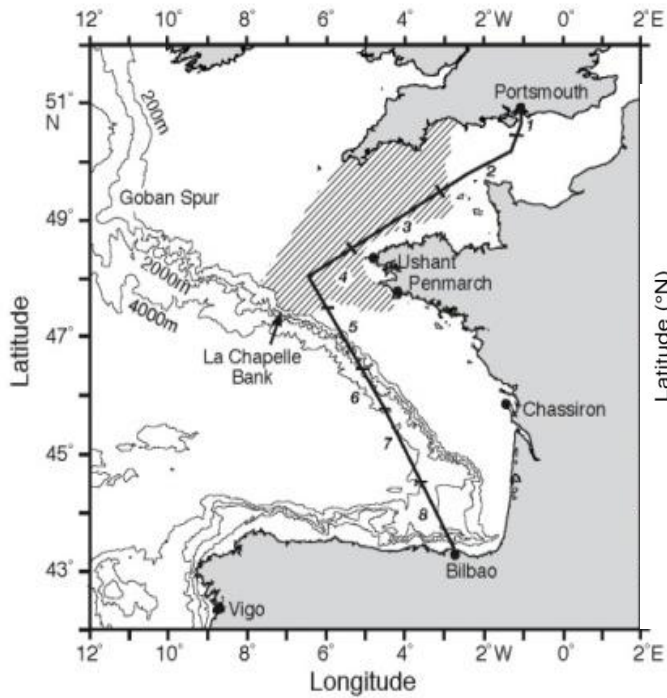
- Intake at 5 metres
- Flow through housing temperature
- Aanderaa thermistor
- Every 15 seconds

Aanderaa thermistor

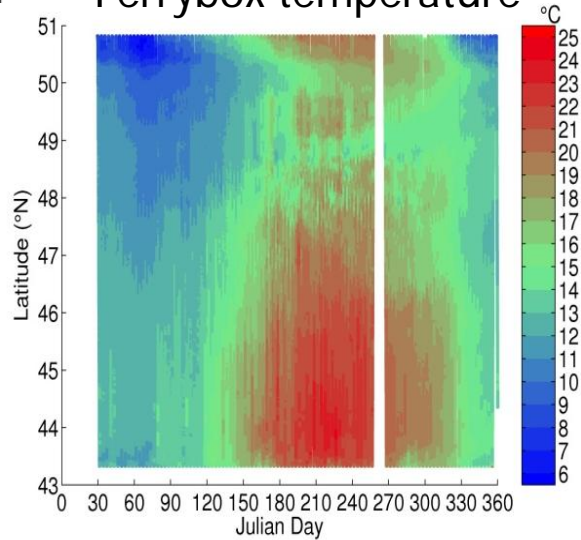


- Results

- Ferrybox – Hull

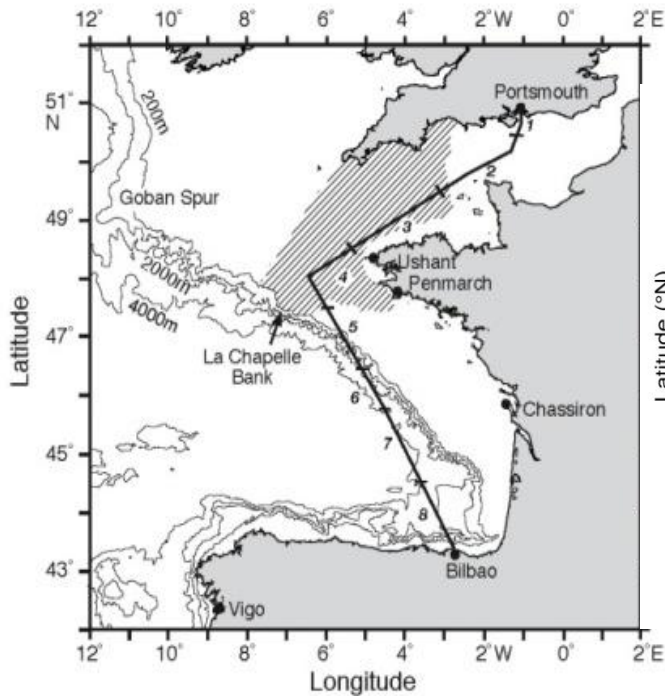


Ferrybox temperature

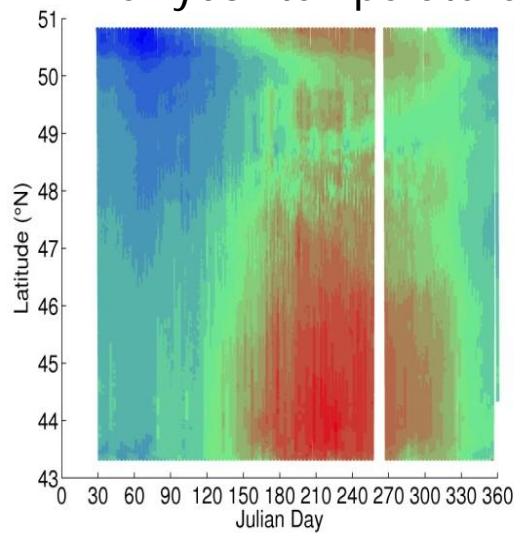


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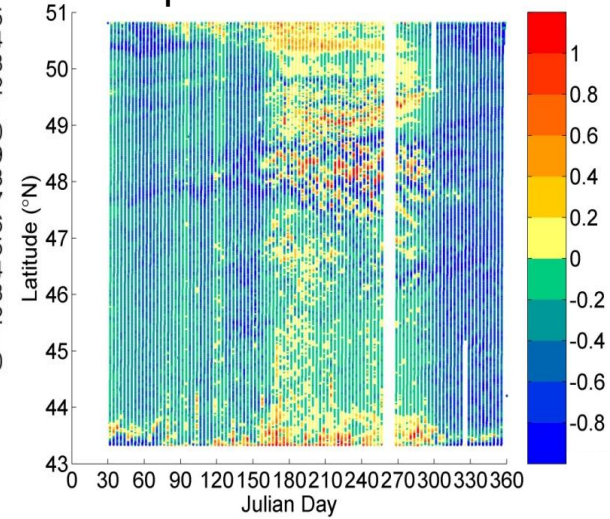
- Ferrybox – Hull



Ferrybox temperature

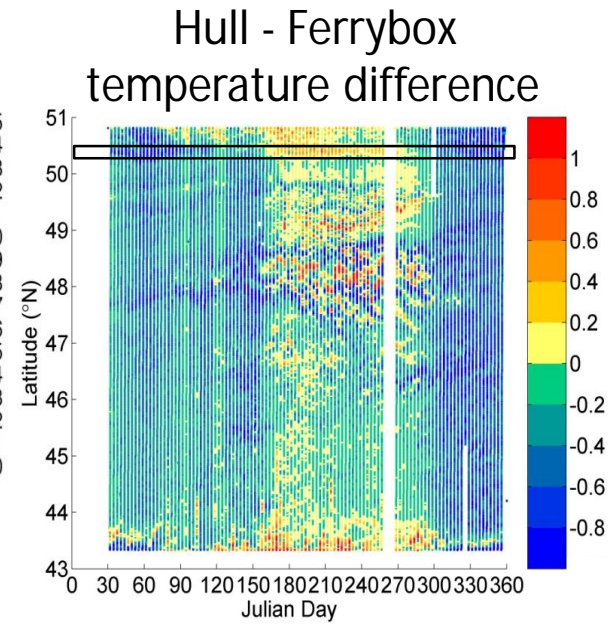
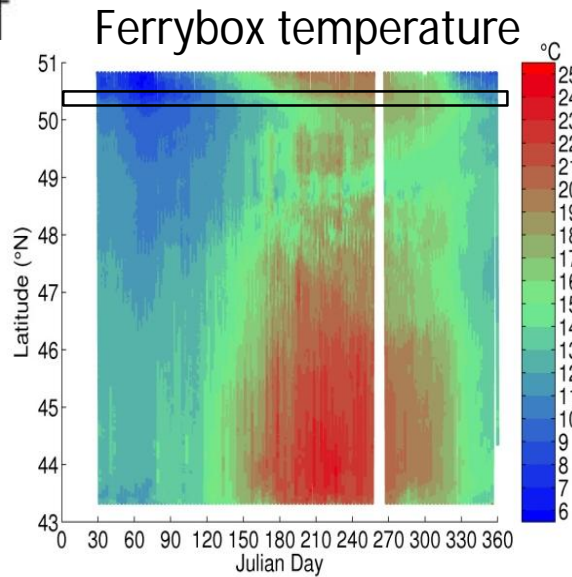
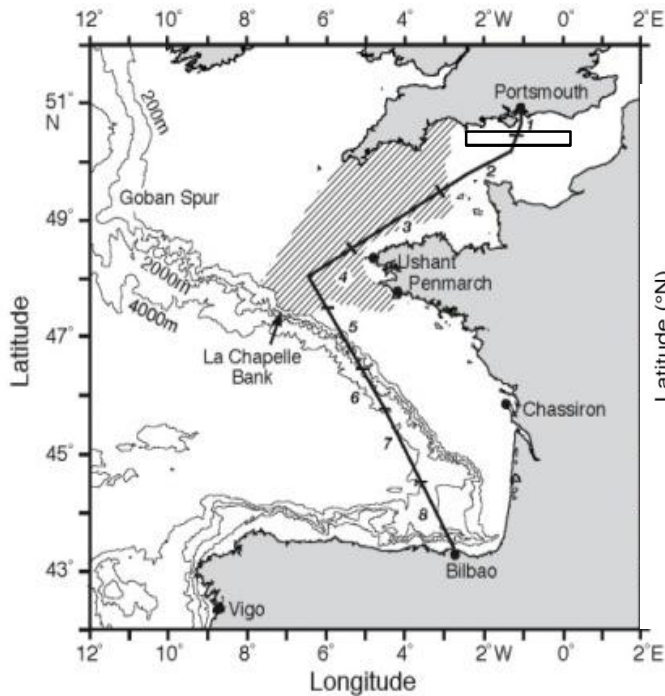


Hull - Ferrybox temperature difference

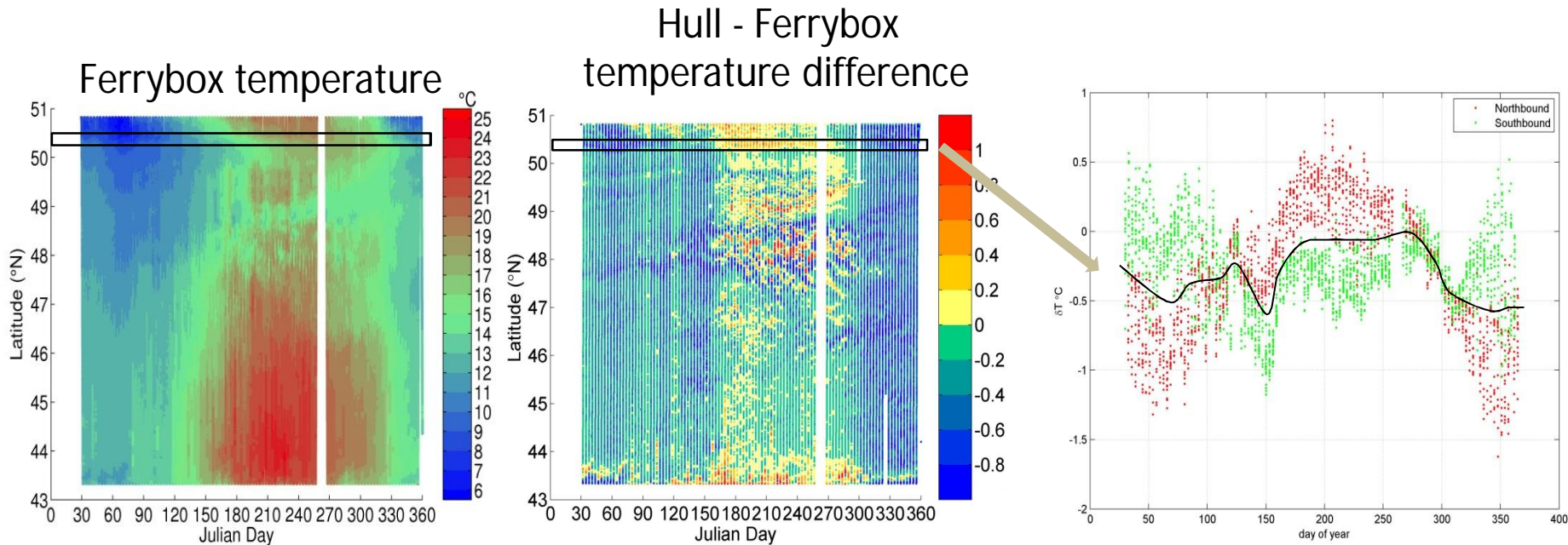


- Results

- Ferrybox – Hull



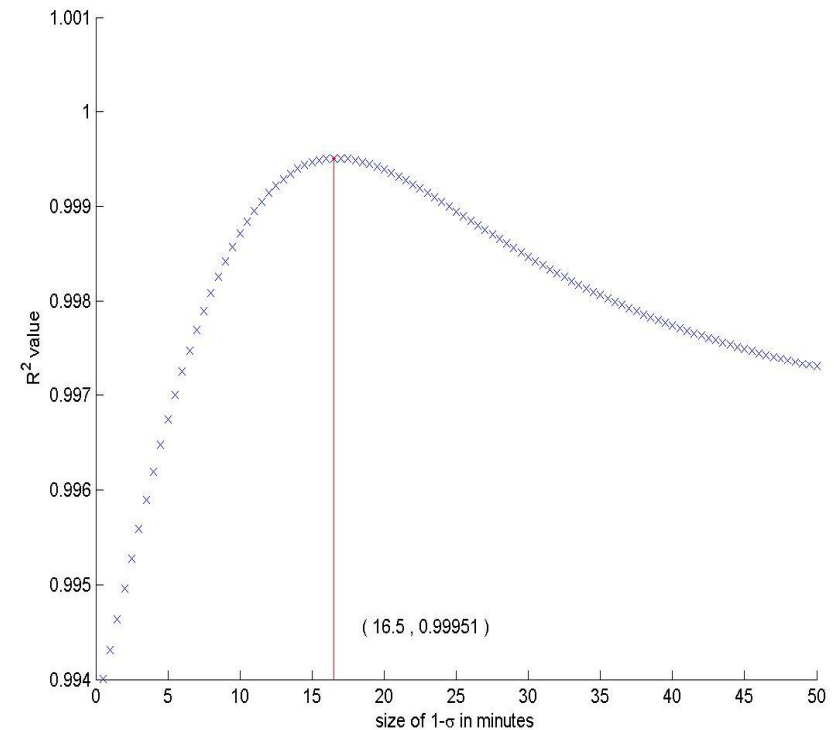
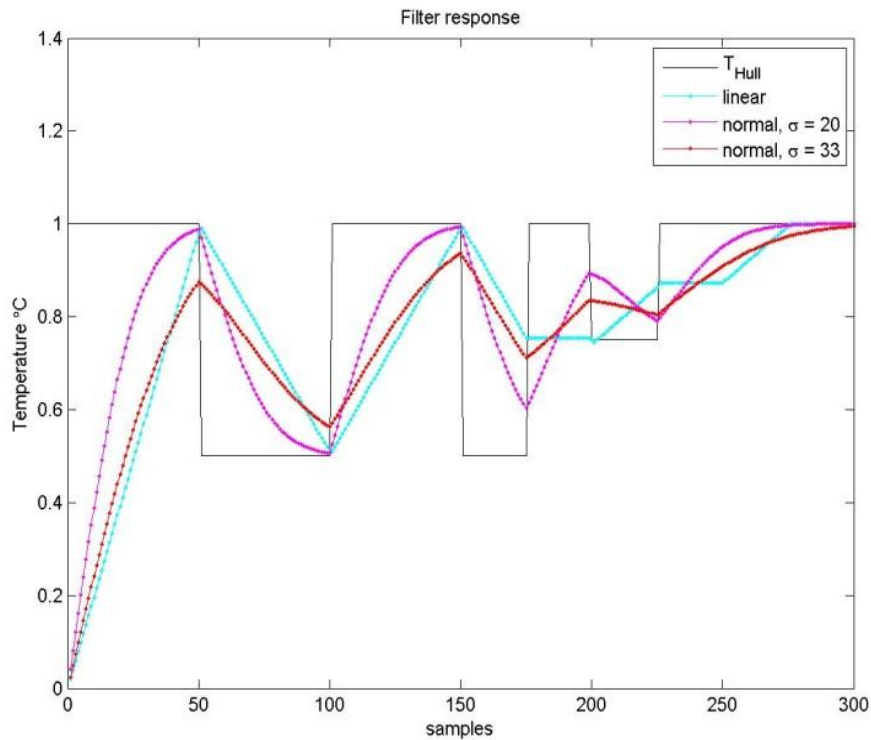
Filter development



- This gives us evidence of a time lag between hull and Ferrybox.
- The hull sensor responds rapidly to temperature changes
- Mixing in the flow through system smoothes the Ferrybox temperature signal.
- So how do we directly compare the sensors that have different levels of smoothing?

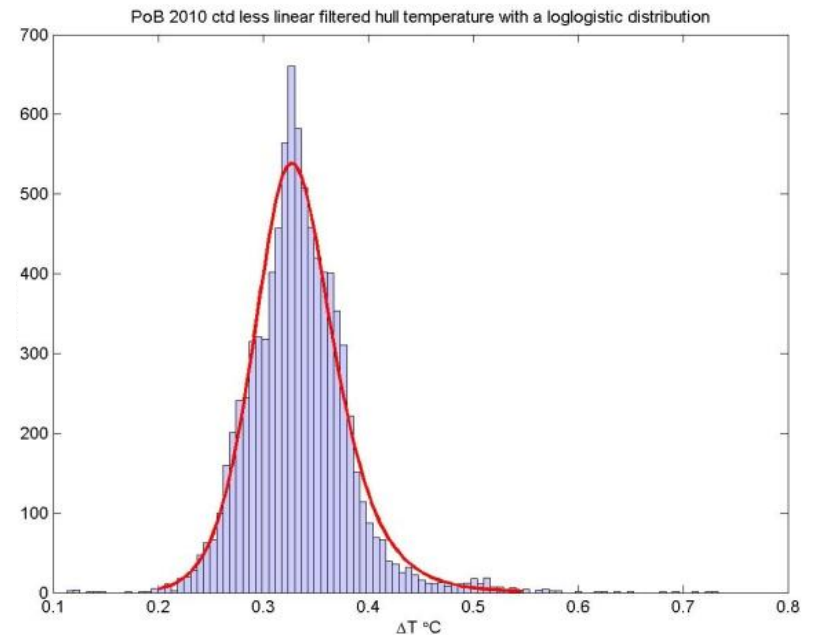
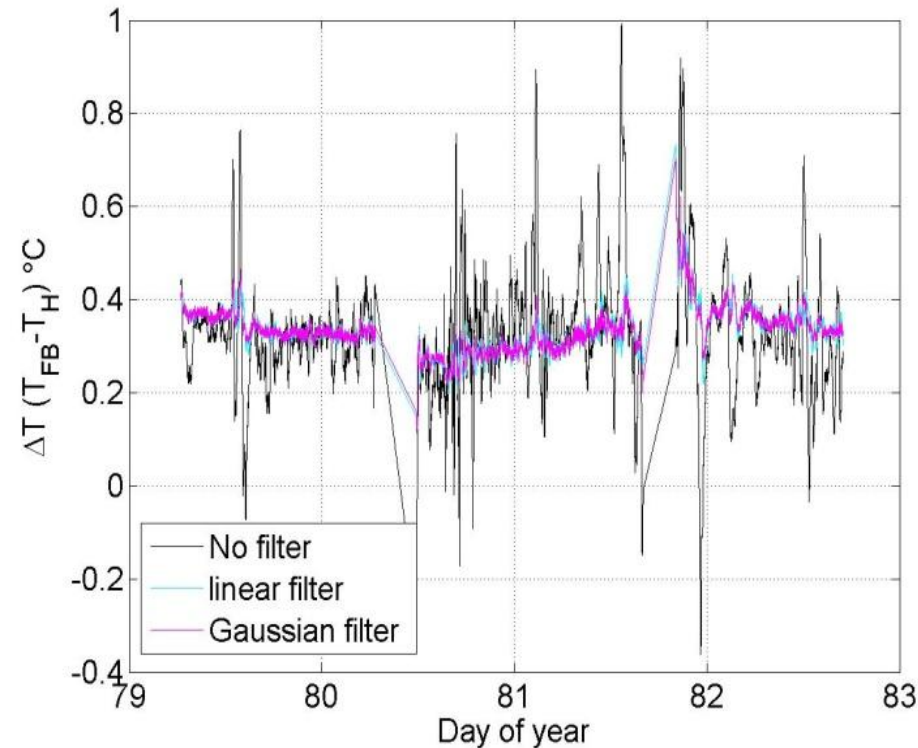
Software filter development

- We apply a software filter to iteratively smooth the signal from the hull sensor.
- The degree of smoothing required is given by a maximum in the regression coefficient.



Filter results

- The software filter dramatically reduces noise generated by comparing data sets that have different levels of smoothing.
- The filtered differences closely follow a loglogistic distribution

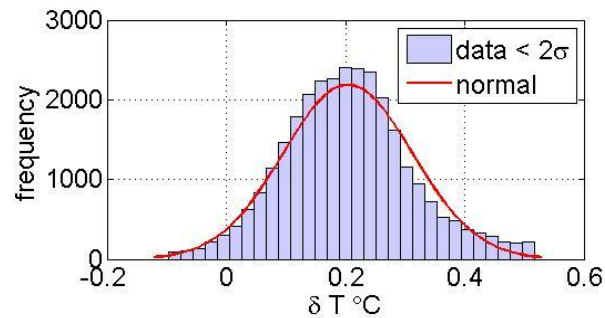


CPR tow data

- The filter enables comparison of data sets that have different levels of smoothing.
- The same technique is applied to the measurements made between Hull and ISAR

All data from 2009

Hull – filtered ISAR

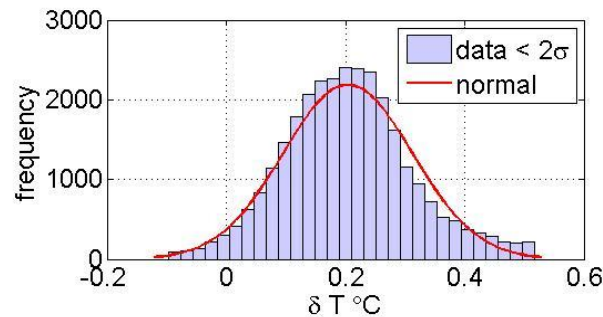


CPR tow data

- The filter enables comparison of data sets that have different levels of smoothing.
- The same technique is applied to the measurements made during the CPR tows during 2009.

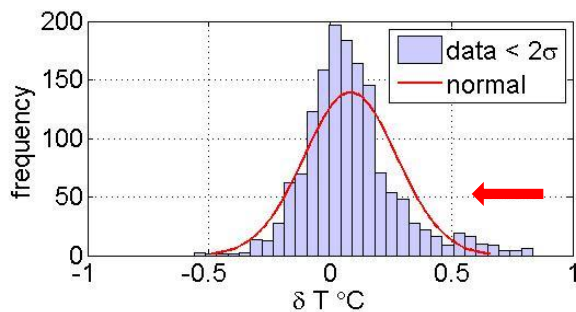
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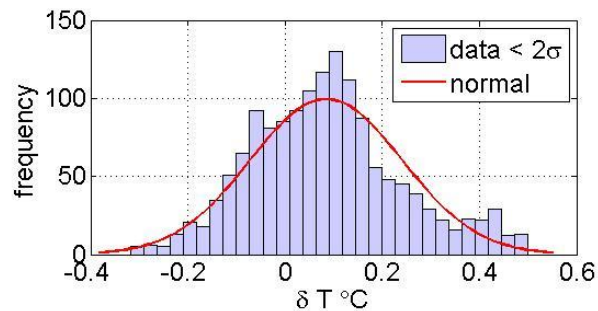


CPR tow data from 2009

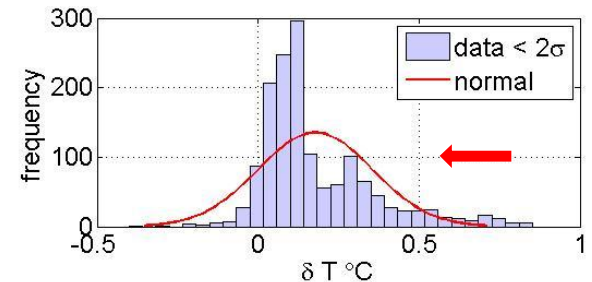
ISAR – filtered CPR



Hull – filtered ISAR



Hull – filtered CPR

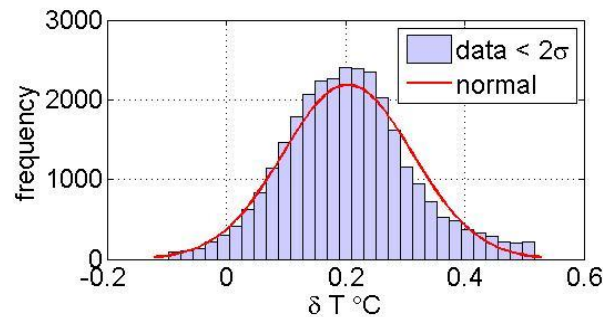


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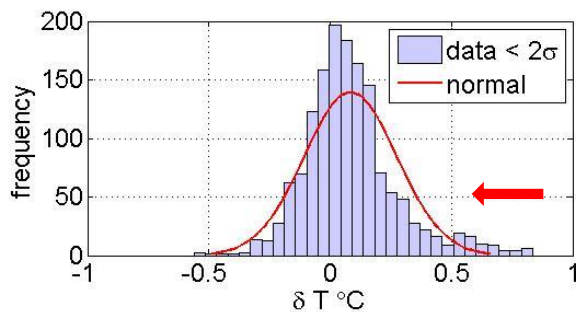
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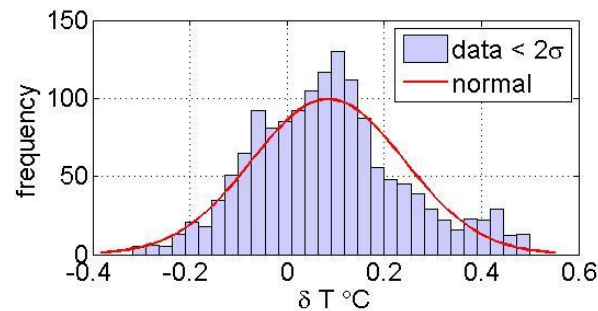


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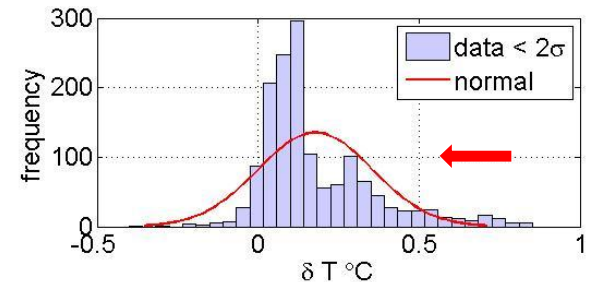
ISAR – filtered CPR



Hull – filtered ISAR



Hull – filtered CPR



- The skew in the distributions indicate the CPR is sometimes not measuring the same water as the ISAR and Hull.
- This can occur in regions of stratification.
- The same technique also resolves diurnal heating effects observable in the ISAR data.

Conclusions

Application of the described software filter

- Enables quantification of the time lag between sensors
- Enables direct comparison of data sets that have different levels of smoothing.
- Quantifies the offsets between sensors
- Allowing the determination (discrimination) of statistical differences from other types of bias.

- And it can

- provide a numerical value that qualifies the degree of mixing occurring within a flow through system that may otherwise be difficult to determine.

- *Conclusions*
- Time lag quantification
- The filter method enables the comparison of data sets that have different levels of smoothing.
- It provides a numerical value that qualifies the degree of mixing that has occurred.
- Offsets have been quantified - determined through filter application has enabled determination(discrimination) of type A and B
- CPR –stratification
- ISAR diurnal skin effects